

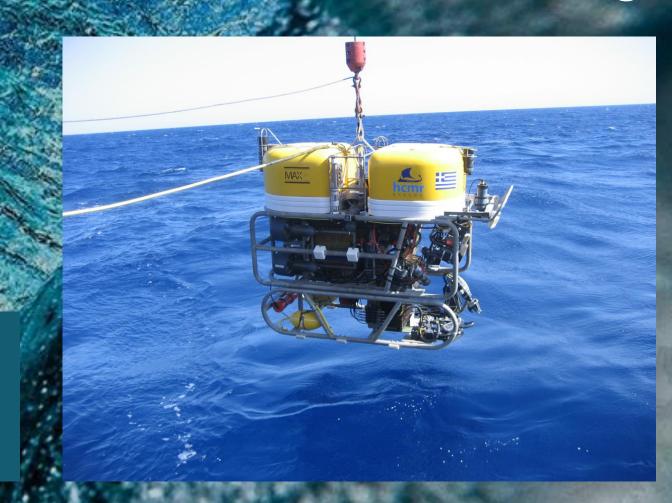
#### **ROV Types**

Hellenic Centre for Marine Research - ROV team



#### ROV's can be classified according

- Horsepower
- Size
- Capabilities!





International Maritime Contractors Association list



**Class I** - Observation ROVs Small vehicles fitted with camera, lights and a sonar only.



Photos @HCMF



International Maritime Contractors Association list

**Class I**— observation ROVs with Payload Option Vehicles fitted with two simultaneously viewable cameras, sonar as standard, and capable of handling additional sensors.







International Maritime Contractors Association list

Class III—Work-class vehicles
Vehicles large enough to carry additional sensors and manipulators



Photos @MBARI's Doc Ricketts ROV



International Maritime Contractors Association list



Class IV—towed and bottom-crawling vehicles (vehicles pulled through the water by a surface craft or winch, and bottom-crawling vehicles using a wheel or track system to move across the seafloor)

**Class V**—prototype or development vehicles



Based upon the ROV weight

OCROV—from the smallest vehicles to submersible weights up to 91 kg

MSROV—submersible weights from 91 kg to 907 kg

WCROV—submersible weights in excess 907 kg



OCROV categories



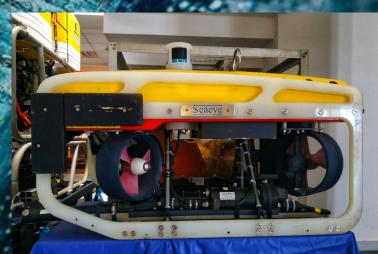
Mini OCROVs—vehicles with submersible weight between 4.5 kg and 32 kg

Photo @HCMR

Micro (or small) OCROVs—those vehicles with a basic weight of less than 4.5 kg



Photo @VFtech spol. s r.o



Large OCROV—vehicles with weights between 32 kg and 90 kg

Photo @HCMR



MSROV categories







**Shallow MSROV**: Low-power vehicles with copper (or fiber) telemetry and ,1000 m depth capability

Deepwater MSROV: Typically deepwater versions of the shallow vehicles and may run single or dual light manipulator systems along with high-voltage power, light-duty electric and hydraulic manipulator systems and fiber-optic telemetry

Heavy MSROV: These are often named "light work class" and typically have electric thrusters, dual medium-duty hydraulic manipulator systems and a hydraulic power unit for operation of medium-duty hydraulic tooling



WCROV categories



**Standard work class:** These vehicles are in the 100 -200 hp range typically used in drill support or light construction



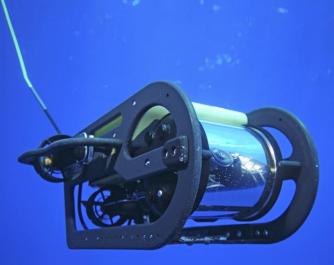
**Heavy work class:** These vehicles are very large and heavy work vehicles of 200 hp or greater for heavy construction work



## hcmr HCMR ROVs

Seabotix LBV-200





Depth Rating 200 m 530 mm Length 245 mm Width 254 mm Height Weight in Air 11 kg

With (4) Brushless DC thrusters – Two (2) forward, one (1) vertical and one (1) lateral.

Speed at surface 3 knots

Camera Tilt 180 degrees Range of View 270 degrees

Camera – Primary 680 line High resolution

color

Video Format NTSC or PAL

Photos @HCMR



#### hcmr HCMR ROVs

Super Achilles ROV



Depth rating 1000 m Length: 720mm 600mm Width: 510 mm Height:

Total weight 100 Kg approx.

2 knots Underwater speed

Propulsion -4 thrusters: Asynchronous

electrically driven.

Video 1 PAL Digital color camera Searchlights 2x250 W – 1x50 W halogen lights

Instrumentation - Fluxgate compass -Echo sounder for altitude monitoring.

-Pressure sensor for depth monitoring

-Built-in imaging sonar; 360° scanning

head; high resolution; 180° 3D

Video-Data Recording VHS - SVHS -CD-DVD-MDV

Arm 3 axis manipulator: in/out, rotation, grip



# hcmr HCMR ROVS

SAAB SEAEYE Falcon



Depth rating 300 m 1000 mm Length 500 mm Height Width 600 mm Weight in air 60 kg Payload 14 kg Forward thrust 40 kgf Lateral thrust 23 kgf Vertical thrust 13 kgf 3 kn Speed > Thruster type \$1-MCT01 Horizontal thrusters Vertical thrusters Auto-depth Auto-heading Video channels Video transmission STP/FO

LED lights (standard quantity) 2

Photos @HCMR



#### hcmr HCMR ROVs

DSSI Max Rover



Depth rating 2000 m 2200 mm Length Height 2000 mm 900 mm Width Weight in air 1100 kg Payload 68 kg Underwater speed: 2.5 knots (fwd/rev),1.5 knots (vert/lat)

Horizontal thrusters Vertical thrusters

Sonars: Tritech Dual Frequency Scanning Sonar (675/1200 KHz) & Tritech Side Scan Sonar (910 KHz)

Autopiloting: course, depth, altitude Positioning system: Trackpoint II USBL

positioning system

4 (2 HD Cameras, 2 Cameras

Pal cameras)

2 x 100 W HID lights Lights

and 4 x 150 W Quartz lights

Manipulation: 2 Hydrolek electro-

hydraulic 5 function manipulators

